Task Name	Group Member	Finish by Date/Due	Sep-15	Oct-15	Nov-15	Dec-15	Jan-16	Feb-16	Mar-16	Apr-16
			1 8 15 22 2	29 6 13 20 27	3 10 17 24	1 8 15 22	29 5 12 19 20	5 2 9 16 23	1 8 15 22 29	5 12 19 26
Individual Behavior										
Research Kilobot Sensors	Jared	September 28, 2015								
Research Kilobot Communication Protocol	Jared	October 12, 2015								
Research Q-bot Image Processing	Ryan/Greg	October 5, 2015								
Research Q-bot Sensors	Ryan/Greg	September 28, 2015								
Reseach Q-bot Communication Protocol	Ryan/Greg	October 19, 2015	ı							
Reseach E-puck Sensors	Brittany	October 26, 2015								
Research E-puck Communication Protocol	Brittany									
Individual Communication										
Research/Test Kilobot - Kilobot	Jared	October 19, 2015	ı							
Research/Test E-puck - E-puck	Brittany	December 14, 2015								
Research/Test Qbot - Qbot	Ryan/Greg	November 2, 2015								
Integrated Communication										
Test Kilobot - E-puck	Jared/Brittany	December 14, 2015								
Test Kilobot - Qbot	Jared/Ryan/Greg	November 16, 2015								
Test E-puck - Qbot	Brittany/Ryan/Greg	December 14, 2015								
Algorithm Design										
Design Linear Based Model	All	December 14, 2015								
Integrated Behavior										
Formation Control Behavior										
Localization	All	January 25, 2016								
Point Convergence	All	January 25, 2016	i							
Leader Follower	All	January 25, 2016								
Flocking Behavior		• .	i					П		
Neighbor Repulsion	All	February 1, 2016	i							
Enpoint Attraction	All	February 1, 2016	i							
Heading	All	February 1, 2016	i							
Testing		, , , , ,						11		
Software Implementation	All	March 7, 2016	ı							
Hardware Implementation	All	March 7, 2016								
Deliverables		,								
Project Proposal - Oral Presentation	All	October 1, 2015	Į.							
Project Proposal - Document	All	October 15, 2015	ı							
Webpage Release	All	October 28, 2015								
Fall Progress Presentation	All	November 19, 2015	i							
Fall Performance Evaluation	All	November 19, 2015	i							
Fall Performance Review	All	Decemeber 3, 2015	i							
Spring Progress Presentation	All	Feburary 18, 2016								
Student Expo Abstract	All	March 18, 2016								
Progject Demostration	All	March 24, 2016	i							
Final Presentation	All	April 7, 2016	i							
Student Expo Poster Printing Deadline	All	April 11, 2016	i							
Student Expo Poster Setup	All	April 12, 2016	j	1						
Sudent Expo Poster Setup  Sudent Expo	All	April 14, 2016	j	1			1			
Final Report (Draft)	All	April 14, 2016 April 14, 2016	j				1			
Final Report	All	April 28, 2016	j				1			
Final Web Page	All	April 28, 2016 April 28, 2016	j				1	11		
	All						1			
Advisory Board Poster Printing Deadline		April 28, 2016					1			
Advisory Board Poster Presentation	All	April 29, 2016			l	l	i	. L		

This week Jared finished his simulations with the follow the leader algorithm for the Kilobots. Upon finishing, he began working to implement the algorithm onto the Kilobots. Brittany has continued work on the E-pucks. Looking into how to control the E-pucks, as well as unbricking them, and working to communicate using the IR sensor with the Kilobots. The "To Workspace" Simulink block only output the last two of thousands of values, so Greg and Ryan troubleshot it. The block worked correctly after conflicting blocks were deleted from the model. They proceeded to graph the positions of all three QBots during a few point consensus tests. One graph included a 3D plot of the (x,y) coordinates of the QBots versus time.