

Progress Update (2/10/16)

Juan Vazquez

Integration of the Ethernet detection and packet classification (Dan's program) is now fully functional in one program. I was able to first generate a text file that could be read by the packet classification program and then I was able to create two separate functions for each.

David Bumpus

I have successfully implemented the visualization of point clouds captured from the VLP-16 using PCL. I am currently working toward successful keypoint detection and feature matching for point-clouds from the VLP-16. I intend to implement a process for interpolating the data. I will continue to work at the same pace.

Daniel Kubik

I can now successfully convert one of my masterBlock objects into many different forms of PCL point clouds; these can be viewed using the PCL 3D-viewer. My next steps are to explore different PCL algorithms for keypoint detection as well as looking into interpolating the point cloud data. I will continue working at the same pace.