

Sony S-Link gateway

Hardware layer, waveforms

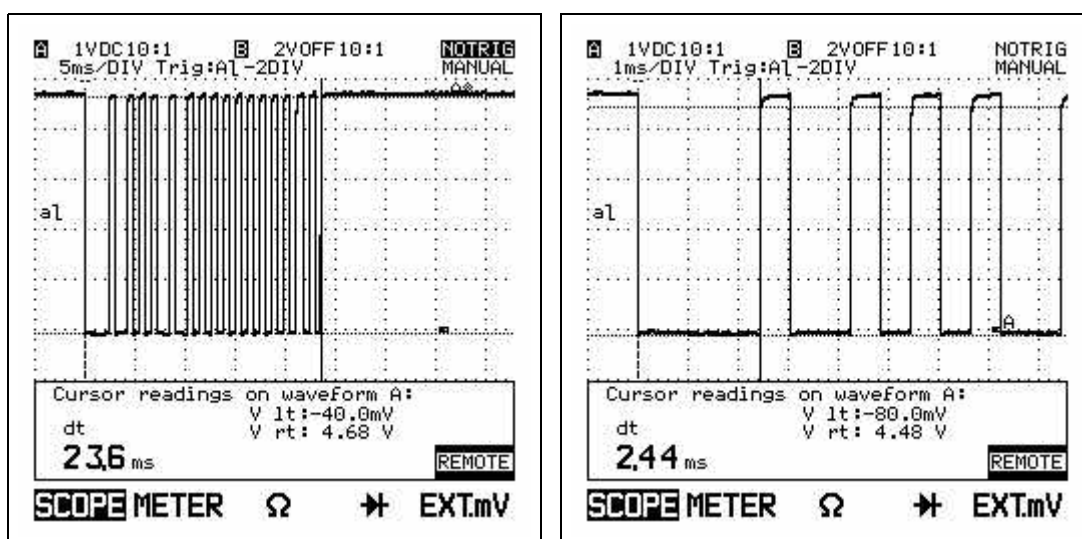
S-Link uses a two wire connection. 3.5mm mono jack connectors connect to Sony S-Link compatible components.

In idle state (99% of the time) the line is hold at 5V by internal pull up. In a short circuit condition current is limit to approx. 44mA. Any participant in communication must tie the line low for multiples of 600uS. This is the internal timebase for all S-Link communication. We differentiate four states:

- Synchronisation
holding the line low for 2400uS indicates the beginning of new transmission
- Zero bit
holding the line low for 600uS indicates a 0
- One bit
holding the line low for 1200uS indicates a 1
- Delimiter
between Sync, Ones and Zeros, the line must be released (return to high level) for 600uS

Synchronisation indicates the beginning of a new transmission. It does not precede every byte. Databits are organized as bytes (8 bit). The most significant bit (MSB) is transmitted first. A transmission consists of 2 ore more bytes, depending on the type of command.

The following waveforms show the message sent by a CDP-CX250 after pressing the play button.



Protocol layer

Most of this work has been done by others. A list of the commands discovered by BigDave you'll find at

<http://www.cc.gatech.edu/people/home/bigdave/cdplayer/control-a1.txt>

Following a part of BigDaves list 'control-a1.txt'

Status messages sent by the player

Now the codes themselves (written in hex unless otherwise noted):

The first byte tells the controller which CD player is talking:

98 = CDP-1
99 = CDP-2
9A = CDP-3

Bytes 2 onward tell you what information or command is being given.

When they are commands:

00 = Play
01 = Stop
02 = Pause
06 = Moving the CD Carosel
08 = Ready
0C = 29 seconds left on current track (Displayed during play)

When they are "Status" or information bytes:

18 = Door Open
2E = Power On
2F = Power Off
50 <Disc#> <Track#> <Length min> <Length sec> = Playing Track
- <Disc#>: 1 byte Discs 1-99 are Binary Coded Decimal (BCD)
 Discs 100-200 are HEX-54d
- <Track#>: 1 byte Tracks are BCD
- <Length minutes>: 1 byte Minutes are BCD
- <Length seconds>: 1 byte Seconds are BCD

52 <Disc#> = Displaying on front panel the track/time/memo info for <Disc#>
- <Disc#>: 1 byte Discs 1-99 are BCD
 Discs 100-200 are HEX-54d

54 <Disc#> = Retrieving <Disc#>, or Loading <Disc#>
- <Disc#>: 1 byte Discs 1-99 are BCD
 Discs 100-200 are HEX-54d

58 <Disc#> = Retrieved <Disc#>, or Loaded <Disc#>
- <Disc#>: 1 byte Discs 1-99 are BCD
 Discs 100-200 are HEX-54d

61 <Disc Capacity> <something else> = Tells the controller something
 about the CDplayer itself.
 I call it the "CD Model
 Identifiers."
- <Disc Capacity>: 1 byte 100 Disc Player is 00 hex
 200 Disc Player is FE hex
 50+1 Disc Player (I am speculating
 it will be 50 or 51 hex)
- <Something else>: 1 byte usually 0B hex

```

70 <00hex> <CD Playing status> <00hex> <Disc#> <00hex>
  - <00hex>: 1 byte Could mean something...but for me it never
              changes.
  - <CD Playing status>: 1 byte (divided into 2 half bytes)
    - Half byte 1: (4 Most Significant bits) blb2b3b4
      - bit 1: 0 = Scanning Discs (happens when you
                open, then close the CD door)
                1 = Discs known (knows which discs
                are loaded and which are not)
      - bit 2: 0 = Play mode: 1 Disc
                1 = Play mode: All Discs
      - bits 3,4: 00 = Play mode: Repeat Off
                  01 = Play mode: Repeat All
                  10 = Play mode: Repeat 1
    - Half byte 2: (4 Least Significant bits) blb2b3b4
      - bits 1-4: 0000 = Normal
                  0001 = Shuffle
                  0010 = Programm

```

Format for commands to send to the CD Player (in hex unless otherwise noted).

The first byte tells which of the 3 possible CD players to execute the command. The format is as follows:

```

90 = Sends command to CD-1
91 = Sends command to CD-2
92 = Sends command to CD-3

```

Bytes 2 onward give the specific command to the CD player

```

00 = Play
01 = Stop
02 = Pause
03 = Toggle Pause
50 <Disc#> <Track#> = Play the song on Disc#, Track#
  - <Disc#>: 1 byte Discs 1-99 are BCD
              Discs 100-200 are HEX-54d
  - <Track#>: 1 byte Tracks are BCD

```

NOTES:

<Disc#>: 1 byte can have 256 unique numbers. Sony ignores disc 00 on the 200 Disc Players. Disc 100 on the 100 Disc Players is represented as 00 hex. Also, their "hacked" format for 200 discs (their format for the 100 disc players is simple, just BCD) allows a total of 201 possible discs. This explains Discs 100-200 being equal to the hex value - 54(base 10) while Discs 1-99 are in BCD. The algorithm to take the byte given for disc# and printing it on a computer screen in base 10 is as follows:

```

//Comment: (hb1 = 4MSB and hb2 = 4LSB of the byte)
if (hb1 > 9)
  print("Disc #" + (16*hb1 + hb2 - 54))
else
  print("Disc #" + (10*hb1 + hb2))

```

<Track#>,<Length min>,<Length sec>: Simple BCD. Algorithm to print in base 10 is as follows:

```

print( 10*hb1 + hb2 )

```

Let's say that CD-1 is playing Disc 148, Track 3, which is 3m 48s

long. The output from the player is (hex): 98 50 CA 03 03 48
Now for Disc 62, Track 14, which is 2m 14s long: 98 50 62 14 02 14

When the unit is first given power, the following information is given:

```
-Power Off  
-CD Model Identifiers: <Disc Capacity> 0B
```

When the On button is first pressed, the following information is given:

```
-Power On  
-Retrieved (or Loaded) Disc Number <Disc#>  
-Retrieved (or Loaded) Disc Number <Disc#>  
-CD Model Identifiers: <Disc Capacity> 0B  
-Displaying on Front Panel the time/track/memo info for: <Disc#>  
-Ready
```

The following commands are discovered by myself, using a gateway described later in this document.

Commands (Byte 2)

08 = next track

09 = next track

20 = Display off

21 = Display on

25 = continous status output

26 = stop outputing status

2e = Power on

2f = Power off

Status (Byte 2)

0E = Power is Off

The gateway

The gateway should fit the following requirements:

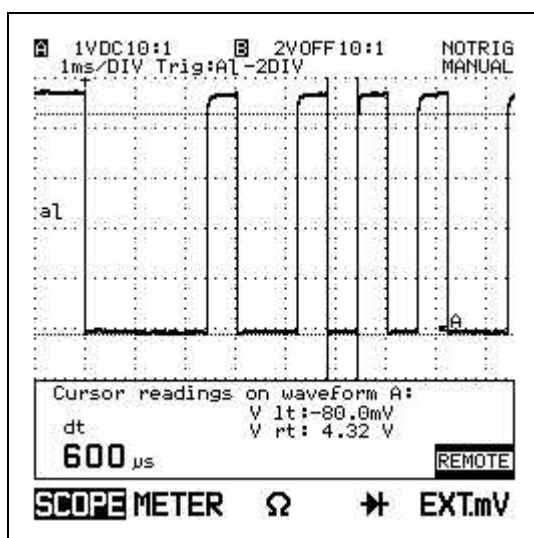
- Translation from S-Link coding to standard 8bit characters (with start and stop bit) and vice versa.
- Standalone operation without a PC. Status information from player are buffered, so the host can request them at any time.
- Flexible host interface, RS232 and/or RS485
- S-Link isolated by opto couplers. This prevents noise from grounding loops between audio equipment and PC.
- Supply from external AC/DC adaptor.

My target system is a DS80520 uC from DALLAS Semiconductor. The DS87520 is a powerful 8bit controller based on Intels 8051 core.

Features:

- 2 Full duplex serial ports
- 3 Timers 16bit
- 5 external interrupts
- Watchdog / Power on reset
- 1kB SRAM on chip
- 16kB (E)PROM on chip

Concepts



Since the delimiter between any line low state is constant, it is not necessary to detect falling and rising edges. The delay between two rising edges can be interpreted as Sync, Ones and Zeros.

A delay of more than 2700uS ($4.5 * 600uS$) is always a synchronisation. Ones are longer than 1500uS and Zeros must have at least 900uS.

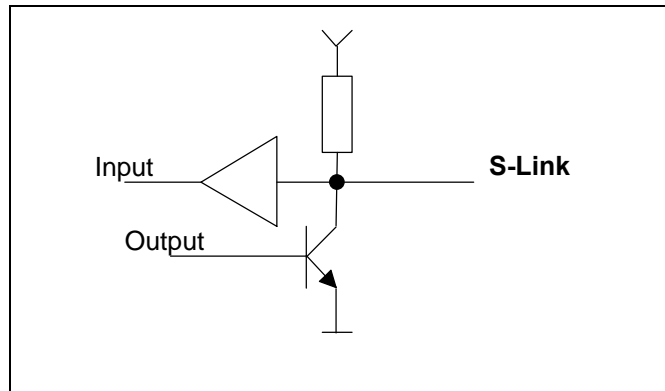
The count of databits is always a multiple of 8. A violation of this rule indicates an error.

S-Link has no bus arbitration logic. Messages can be sent at any time by any participant. Bus collision may occur. Because there is not much traffic, this happens extremely rare. Checking the receiver state immediately before starting a new

transmission prevents from collisions in nearly all cases. Verification is the Job of the application programm or the operator.

Hardware

Data transmission uses 5V TTL levels. An open collector output with an optional pull up resistor is all you need to send data over the S-Link. The IO stage of the 87C520 fits this requirements directly. The same IO could be used for monitoring the line for receiving.



But why using 2 IO pins for input and output ? Opto couplers for isolating the S-Link from supply and other links are working unidirectional. If your PC is grounded and the CD is connected to an Amp which itself is wired to a tuner with connection to an antenna somewhere in town - then isolation might be a good idea.

Software

Sending and receiving from/to S-Link and RS232 is handled in interrupt service routines. The S-Link receiver saves all incoming characters in buffer. After a timeout (50mS) from the last data bit, a flag tells the main program that a message has arrived and is available in the input buffer. The main program copies the buffer to the RS232 output queue and activates the sender. Every data byte is sent as two nibbles in ASCII-HEX notation. Value 255 would be sent as string 'FF'. Transmission string is terminated by a CR.

Communication in the other direction works in a similar manner. The RS232 receiver (interrupt handler) reads a CR terminated ASCII-HEX string from the serial port, converts to binary data, stores them in a buffer and informs the main program. The main program copies the buffer to the S-Link output queue and activates the sender. 50mS after the last incoming data bit from S-Link the sender starts transmission.

```
// Author   : Rolf Eigenheer                               rolf_eigenheer@bluewin.ch
// Compiler : Keil C51
// Target   : DS87C520 @14,7456MHz

#pragma CODE_DEBUG INTVECTOR OBJECTTEXTEND SYMBOLS CODE SMALL PL(10000) PW(120) ROM(LARGE)
#pragma NOINTPROMOTE

#include <ABSACC.H>
#include <REG520.H>
#include <CTYPE.H>
#include <INTRINS.H>

code char *Logo1 = "+-----+" \
                   "| S-LINK   |" \
                   "| Gateway |" \
                   "| RS232-RS485 |" \
                   "+-----+" \
                   "| V0.10   |" \
                   "| Er /21.02.98 |" \
                   "+-----+";

code char *Logo2 = "+-----+" \
                   "| (c)1998 |" \
                   "| Rolf Eigenheer |" \
                   "| CH8462 Rheinau |" \
                   "+-----+";

/*****
PIN Definitionen
*****/

sbit _LED1      = P1^0;
sbit _LED2      = P1^1;
sbit RXD1       = P1^2;
sbit TXD1       = P1^3;
sbit INT2       = P1^4;
sbit _INT3      = P1^5;
sbit INT4       = P1^6;
sbit _INT5      = P1^7;

sbit RXD0       = P3^0;          // RS232 RxD use MAX233 to convert levels to +/-12V
sbit TXD0       = P3^1;          // RS233 TxD use MAX233 to convert levels to +/-12V
sbit _INT0      = P3^2;
sbit _INT1      = P3^3;
sbit SDA        = P3^6;
sbit SCL        = P3^7;

#define SWITCHES ~P2

#define _TXEN_0   T0
#define SLINK0_OUT INT4 // Output to S-Link (use opto couplers)
#define SLINK0_IN INT0 // Inverted Input from S-Link (use opto couplers)
// Inversion is necessary because Int0 triggers on
// the falling edge. We are interested on S-Link
// rising edges.

/*****
******/

code unsigned char Hex[0x10] = {0x30,0x31,0x32,0x33,0x34,0x35,0x36,0x37,
                                0x38,0x39,0x41,0x42,0x43,0x44,0x45,0x46};

// RS232 communication variables
unsigned char RxCount = 0;
unsigned char TxCount = 0;
xdata unsigned char RxBuf[0x100];
xdata unsigned char TxBuf[0x100];

// S-Link communication variables
unsigned char InCount = 0;
unsigned char OutCount = 0;
xdata unsigned char InBuf[0x100];
xdata unsigned char OutBuf[0x100];
bit StartSending = 0;
```

```

/*****
Interrupthandler der Serieschnittstelle  LoPrio
*****/
#pragma rb(1)

void HandleLink0 () interrupt 4 using 1 {    /* Handles Rx and Tx Interrupts */
    static unsigned char RC      = 0;
    static unsigned char TC      = 0;
    static bit          Rx2ndNib = 0;
    static bit          Tx2ndNib = 0;

    if(_testbit_(TI)) {
        if(TC < TxCount) {
            if(Tx2ndNib)
                SBUF = Hex[TxBuf[TC++] & 0x0f];          // Send lower Nibble
            else
                SBUF = Hex[TxBuf[TC] / 0x10];            // Send higher Nibble
            Tx2ndNib = !Tx2ndNib;
        }
        else {
            if(TxCount)
                SBUF = 0x0d;
            Tx2ndNib = 0;
            TC      = 0;
            TxCount = 0;
        }
    }

    if(_testbit_(RI)) {
        if(SBUF == 0x0d) {
            RxCount = RC;
            Rx2ndNib = 0;
            RC      = 0;
        }
        else {
            if(isxdigit(SBUF)) {
                if(Rx2ndNib)
                    RxBuf[RC++] |= toint(SBUF);          // lower Nibble
                else
                    RxBuf[RC] = toint(SBUF) * 0x10;      // higher Nibble (first)
                Rx2ndNib = !Rx2ndNib;
            }
        }
    }
}

void HandleLink1 () interrupt 7 using 1 {    /* Handles Rx and Tx Interrupts */
    if(_testbit_(TI_1)) {
    }
    if(_testbit_(RI_1)) {
    }
}

#pragma rb(0)

/*****
Link0 Intr0 Timer0 Interupt  HiPrio
*****/
#define TSync  2950
#define TOne   1845
#define TZero  1110

#pragma rb(2)

unsigned char BitMask  = 0x80;
unsigned char ByteCount = 0x00;
bit          TimedOut   = 0;
bit          Receiving  = 0;
bit          Sending    = 0;

ProcessMsg() {
    if(ByteCount && (BitMask == 0x80)) {
        InCount = ByteCount;
    }
    ByteCount = 0x00;
    BitMask   = 0x80;
}

```



```

void HandleSLinkTimeOut() interrupt 1 using 2 {           // timer0
  if(!Sending) {
    TimedOut = 1;
    ProcessMsg();
    Receiving = 0;
    EX0      = 1;           // enable Receiver
  }
  if(!SLINK0_OUT) {           // if was a data bit
    SLINK0_OUT = 1;         // GAP
    TH0 = 0xFD;           // 600uS until overflow
    TL0 = 0x1D;
  }
  else if(StartSending) {
    if(SLINK0_IN) return;   // if link is busy return
    if(SLINK0_IN) return;
    if(SLINK0_IN) return;
    if(SLINK0_IN) return;
    if(SLINK0_IN) return;
    SLINK0_OUT = 0;         // Syncbit
    TH0 = 0xF4;           // 2400uS until overflow
    TL0 = 0x79;
    ByteCount = 0x00;
    BitMask = 0x80;
    Sending = 1;
    StartSending = 0;
    EX0 = 0;             // disable Receiver
  }
  else if(Sending) {
    if(ByteCount < OutCount) {           // if was Gap
      SLINK0_OUT = 0;           // mark
      if(OutBuf[ByteCount] & BitMask) {
        TH0 = 0xFA;           // 1200uS until overflow
        TL0 = 0x3C;
      }
      else {
        TH0 = 0xFD;           // 600uS until overflow
        TL0 = 0x1D;
      }
      BitMask >>= 1;
      if(BitMask == 0x00) {
        BitMask = 0x80;
        ByteCount++;
      }
    }
    else {
      ByteCount = 0x00;
      BitMask = 0x80;
      OutCount = 0;
      Sending = 0;
      EX0 = 1;           // enable Receiver
    }
  }
}

void HandleSLinkIntr () interrupt 0 using 2 {           // int0
  unsigned int TimerVal;
  if(!Sending) {
    TR0 = 0; TimerVal = 0x100*TH0 + TL0; TR0 = 1;
    if(INT0) return;           // return if only a spike
    if(INT0) return;
    if(INT0) return;
    if(INT0) return;
    if(INT0) return;
    if(TimedOut || (TimerVal > TSync)) {           // is Synchronisation
      TH0 = TL0 = 0x00; TF0 = 0;
      TimedOut = 0;
      ProcessMsg();
      Receiving = 1;
    }
    else if(TimerVal > TOne) {           // is bit One
      TH0 = TL0 = 0x00; TF0 = 0;
      InBuf[ByteCount] |= BitMask;
      BitMask >>= 1;
      if(BitMask == 0x00) {
        BitMask = 0x80;
        ByteCount++;
      }
    }
  }
}

```

```

    else if(TimerVal > TZero) { // is bit Zero
        TH0 = TL0 = 0x00; TF0 = 0;
        InBuf[ByteCount] &= ~BitMask;
        BitMask >>= 1;
        if(BitMask == 0x00) {
            BitMask = 0x80;
            ByteCount++;
        }
    }
}

#pragma rb(0)

/*****
Timer2 Interupt LoPrio 0.25ms
*****/
#pragma rb(1)

void Timer2() interrupt 5 using 1 {
    static unsigned int TCount = 0x00;
    TF2 = 0;
    if(++TCount >= 400) { /*100ms */
        TCount = 0;
        _LED1 = !_LED1;
    }
}

#pragma rb(0)

/*****
Initialisierung der Schnittstelle und der Timer
*****/

void InstallRS485(unsigned char Reload, bit Bit9) {
    TCON &= 0x0f; /* Stop Timer0 Timer1 */

    ES = 0; /* Disable Serial Interupt */
    PCON &= 0x7f; /* Reset SMOD */
    SCON = 0x40; /* Serialport Operating Mode */
    SM0 = Bit9; /* 9bit */
    SM2 = 0;
    TB8 = 0;

    REN = 1; /* Enable RS232 Receiver */
    PS = 0; /* RS232 low Priority */
    ES = 1; /* Enable RS232 Interupt */

    ES_1 = 0; /* Disable Serial Interupt */
    WDCON &= 0x7f; /* Reset SMOD_1 */
    SCON1 = 0x40; /* Serialport Operating Mode */
    SM0_1 = Bit9; /* 9bit */
    SM2_1 = 0;
    TB8_1 = 0;

    REN_1 = 1; /* Enable RS232 Receiver */
    PS_1 = 0; /* RS232 low Priority */
    ES_1 = 1; /* Enable RS232 Interupt */

    ET0 = 0; /* Disable Timer0 Interupt */
    ET1 = 0; /* Disable Timer1 Interupt */
    TMOD = 0x21; /* Timer0 16Bit - Timer1 Auto-Reload */
    TH1 = TL1 = Reload; /* Reload-Value Timer1 */
    TH0 = TL0 = 0x00; /* Reset Timer0 */
    PT0 = 0; /* Timer0 low Priority */
    PT1 = 0; /* Timer1 low Priority */
    TR0 = 1; /* Start Timer0 (free running 16bit) */
    TR1 = 1; /* Start Timer1 (Baud Rate Generator) */
}

void InstallSLink() {
    PX0 = 1; /* Ext0 High Priority */
    IT0 = 1; /* Ext0 Edge Triggered */
    EX0 = 1; /* aktiviere ExtInt0 */
    PT0 = 0; /* Timer0 low Priority */
    ET0 = 1; /* Enable Timer0 Interupt */
    TR0 = 1; /* Start Timer0 (free running 16bit) */
}

```

```

unsigned int InstallTimer(float fosz, float interval) {      /* Installs a periodic Interrupt
*/
    unsigned int reload;
    reload = (0xffff - (interval * (fosz / 12)));
    RCAP2L = reload;
    RCAP2H = reload >> 0x08;
    T2CON = 0x04;
    PT2   = 0;
    ET2   = 1;
    return(reload);
}

#define ENABLERTCLK   ET2 = 1;
#define DISABLERTCLK ET2 = 0;

/*****
Allgemeine Funktionen
*****/

void SwitchOnChipRAM(bit On) {
    PMR &= ~DME1;      /* 0400H-FFFF EXTERN */
    if(On)
        PMR |= DME0;   /* 0000H-03FF INTERN */
    else
        PMR &= ~DME0;  /* 0000H-03FF EXTERN */
}

void SwitchALE(bit On) {
    if(On)
        PMR &= ~ALEOFF;
    else
        PMR |= ALEOFF;
}

#pragma DISABLE
void InitWatchdog() { /* ca. 500mS Timeout */
    CKCON |= WD1;
    CKCON &= ~WD0;
    TA = 0xaa;
    TA = 0x55;
    RWT = 1;
    TA = 0xaa;
    TA = 0x55;
    EWT = 1;
}

#pragma DISABLE
void WDTrigger() {
    TA = 0xaa;
    TA = 0x55;
    RWT = 1;
}

/*-----
Timing Functions DS87C520 Optimized 14.7456MHz
-----*/

void Delay10uS (unsigned int DTime) { /* 10uS Delay bei 14.xxMHz */
    while(DTime-->0) {
        _nop_(); _nop_(); _nop_();
        _nop_(); _nop_(); _nop_();
        _nop_(); _nop_(); _nop_();
        _nop_(); _nop_(); _nop_();
        _nop_(); _nop_(); _nop_();
        _nop_(); _nop_(); _nop_();
        _nop_(); _nop_(); _nop_();
        _nop_(); _nop_(); _nop_();
    }
}

void Delay1mS (unsigned int DTime) {
    while(DTime-->0) {
        WDTrigger();
        Delay10uS(100);
    }
}

```

```
/*#####  
#####*/
```

```
Reset() {  
    SwitchALE(0);  
    SwitchOnChipRAM(1);  
    InitWatchdog();  
    InstallRS485(0xff,0);  
    InstallTimer(14.7456e6,0.25e-3);          /* 0.25mS */  
    InstallSLink();  
    EA = 1;  
}  
  
main() {  
    Reset();  
  
    while(1) {  
        WDTrigger();  
        if(RxCount) {  
            OutCount = 0;  
            while(RxCount-->0) {  
                OutBuf[OutCount] = RxBuf[OutCount];  
                OutCount++;  
            }  
            RxCount = 0;  
            StartSending = 1;  
        }  
  
        if(InCount) {  
            TxCount = 0;  
            while(InCount-->0) {  
                TxBuf[TxCount] = InBuf[TxCount];  
                TxCount++;  
            }  
            InCount = 0;  
            TI = 1;  
        }  
    }  
}
```